GALERKIN METHODS FOR PDES

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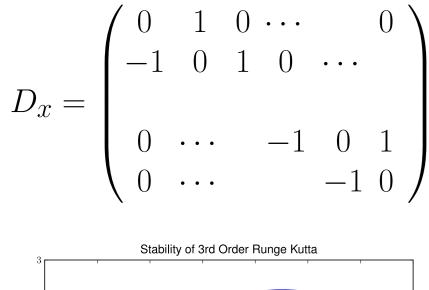
Abstract

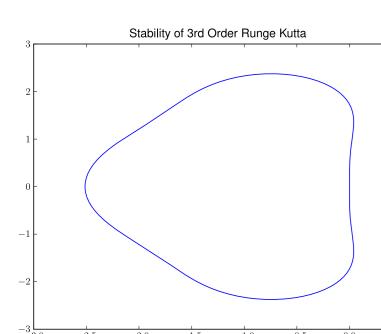
Spectral representations are possible with any number of polynomial approximations of a function. Typically collocation methods are used to minimize programming effort, but more accurate methods known as Galerkin Methods are available. Here we examine Galerkin methods for solving PDEs, comparing them to methods taught in ESAM446-1 and -2.

Goals

- 1. Explore alternatives to Finite Differences, Fourier, and Chebyshev Differentiation: Galerkin, Nodal Continuous Galerkin, and Nodal Discontinuous Galerkin
- 2. Build a basis for implementing spectral element methods
- 3. Write a lot of numerical Python code

Background: Finite Difference Methods and Timestepping Scheme





Williamson's 3^{rd} order, low storage Runge Kutta scheme for wave equation(Stability $\lambda_{\max} \Delta t$ <

Input: t_n , Δt , u, Dfor i = 1 to 3 do do $t \leftarrow t_n + b_m \Delta t$ $\dot{u} \leftarrow TimeDerivative(u, D)$ for j = 0 to N - 1 do do $G_j \leftarrow a_m G_j + \dot{u}$

$u_j \leftarrow u_j + g_m \Delta t G_j$ end for end for $\dot{u} \leftarrow \text{dot(D,F)}$ return \dot{u}

References:

- I. Kopriva, Implementing Spectral Methods for Partial Differential Equations
- 2. Langtangen, Python Scripting for Computational Science
- 3. LeVeque, Finite Difference Methods for Ordinary and Partial Differential Equations
- 4. Patera, A spectral element method for fluid dynamics: laminar flow in a channel expansion
- 5. Recktenwald, Numerical Methods in MATLAB
- 6. Trefethen, Spectral Methods in MATLAB

Alternative Basis Sets and Equations

Polynomial Representations

• Fourier:

$$\Phi = \sum \Phi_n e^{inx}$$

• Chebyshev:

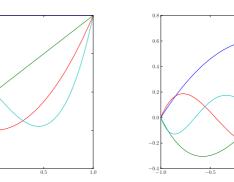
$$\Phi = \sum \Phi_n \cos(n \cos^{-1} x)$$

• Legendre:

$$\Phi = \sum \Phi_n \ell(x)$$

• Modified Legendre:

$$\Phi = \sum \Phi_n \frac{L_k(x) - L_{k+2}(x)}{\sqrt{4k+6}}$$



Uniform Points

0.0

Uniform Points

0.0

0.5

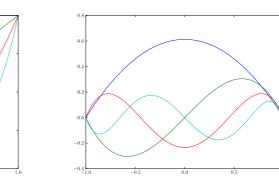
Quadrature nodes and weights

• Legendre-Gauss-Lobato

Chebyshev-Gauss-Lobato

• Legendre-Gauss

• Chebyshev-Gauss



Weak Forms

Collocation and Galerkin Methods

- $\bullet \varphi_t + \varphi_x = \nu \varphi_{xx}$
- $\varphi(x,t) \approx \Phi(x,t) = \sum \Phi_n h_n(x)$

- $\bullet \dot{\Phi}_j + \mathcal{D}\Phi_j = \nu \mathcal{D}^2 \Phi_j$
- $\bullet \, \dot{\Phi}_j = -\mathcal{D}(\Phi_j \nu \mathcal{D}\Phi_j)$

 $\bullet \varphi_t + \varphi_x = \nu \varphi_{xx}$

 $u(\varphi_x\phi_x)$

 $\bullet (\varphi_t, \phi) + (\varphi_x, \phi) = \nu(\varphi_{xx}\phi)$

 $\bullet \varphi = \sum \hat{\Phi}_k \phi_k$

Continuous vs. Noncontinous Galerkin

No need to evaluate inner products analytically; use quadrature

- $\dot{\Phi}_j w_j + \sum w_k \Phi'_k \ell'(x_k) = 0$ $\dot{\Phi}_j + \sum \Phi_n \sum w_k \ell'(x_k) \ell'(x_k) = 0$

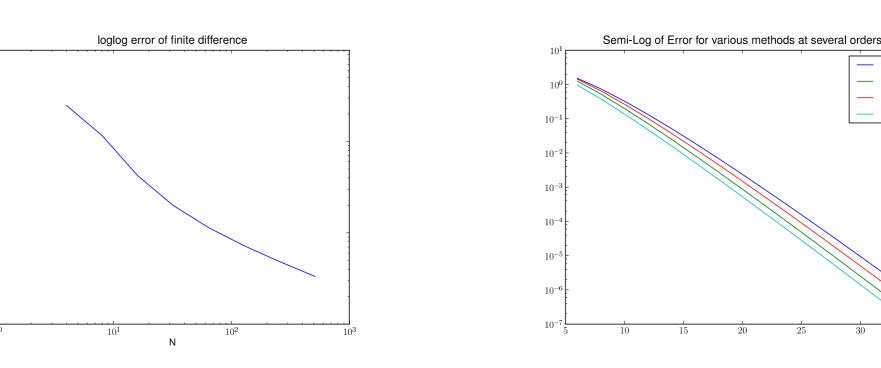
No need to satisfy BCs with test functions

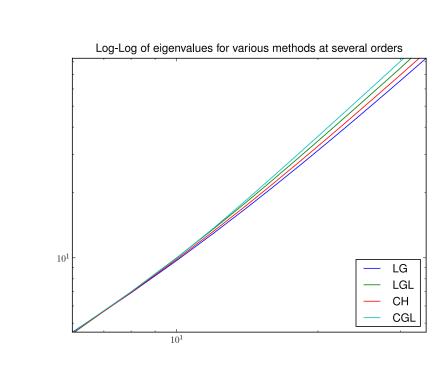
- $(\Phi_t, \ell_j) + \Phi \ell_j |_{-1}^1 (\Phi, \ell'_j) = 0$
- $(\Phi_t, \ell_j) + \Phi(1)\ell_j(1) g(t)\ell_j(-1) (\Phi, \ell'_j) = 0$

Contributions to Kopriva Errata

- Pages 98 and 116, Algorithms 42 and 50 have the same name, CollocationStepByRK3
- Page 115, The PDE in Equation 4.77 should read $\phi_t = k^2 \phi_{xx}$ instead of $\phi_t = \phi_{xx}$ to be consistent with the solution given in 4.82.
- Page 127, Algorithm 53 should have $\Phi \leftarrow 0$ instead of $U \leftarrow 0$
- Page 133, Algorithm 57's summand in the inner loop should be $D_{k,n}D_{k,j}w_k$ to be consistent with eq 4.123
- Page 141, Algorithm 62; dg.Time-Derivative should be dg.DGTime-Derivative, or the Procedures list in 58 should be changed
- Page 213, Algorithm 91; LegendreGaussNodesAndWeights here takes a parameter N, in definition it takes only x, xj, and w. Same with PolynomialDerivative-Matrix.
- Page 215, Algorithm 93: ExternalState calls in η block are missing commas, muddles ' Q^L -1' vs

Differentiation Performance





Summary

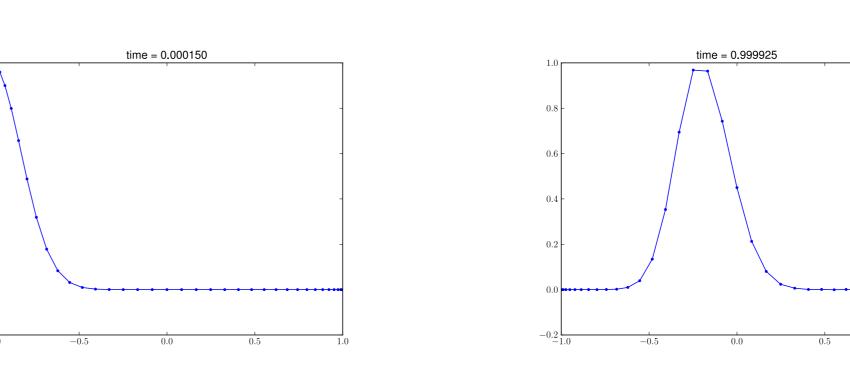
• Large eigenvalues require small

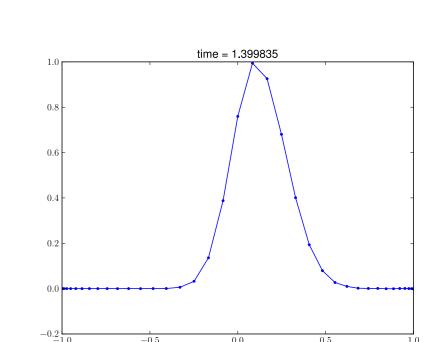
• But great approximations for N = O(30)

• Finite differences, not great for N = O(512)

PDE Performance

Wave equation Forced at x = -1





Methods Implemented

FourierDerivativeMatrix MxVDerivative LegendrePolynomial ChebyshevPolynomial LegendrePolynomialAndDerivative LegendreGaussNodesAndWeights LegendreGaussLobattoNodesAndWeights FourierGalerkinStep ChebyshevGaussNodesAndWeights ChebyshevGaussLobattoNodesAndWeightsFourierGalerkinDriver

BarycentricWeights LagrangeInterpolation PolynomialInterpolationMatrix InterpolateToNewPoints

PolynomialDerivativeMatrix mthOrderPolynomialDerivativeMatrix Fourier Collocation Time Derivative FourierCollocationStepByRK3 FourierCollocationDriver AdvectionDiffusionTimeDerivative

EvaluateFourierGalerkinSolution CollocationStepByRK3 LegendreCollocationIntegrator LagrangeInterpolatingPolynomials DGConstructor

DGDerivative InterpolateToBoundary DGTimeDerivative DGStepByRK3 DGDriver initialValues AlmostEqual TriDiagonalSolve CGDerivativeMatrix GalerkinStepByRK3 CGDerivativeMatrixIntegrator

TDerivative LegendrePolynomialAndDeriv